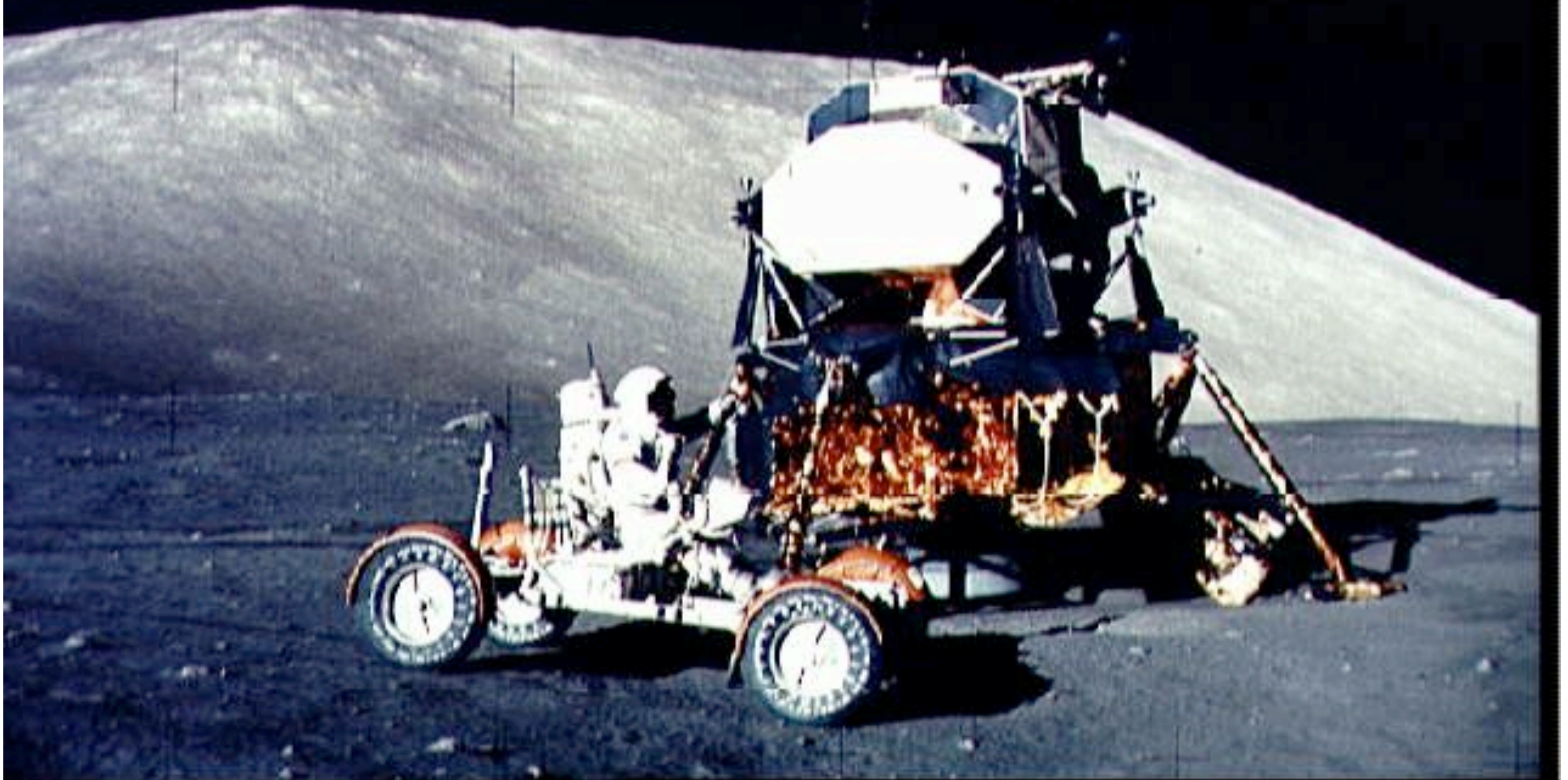


Human Systems & Robotics

Dr. Rob Ambrose, NASA JSC

November 2007



A photograph of the lunar surface, showing a vast, desolate landscape with a large, dark, cratered hill in the background. The foreground is covered in grey, dusty soil with small rocks and craters. In the distance, on the right side, a small, white, four-wheeled vehicle (the Lunar Roving Vehicle) is parked. The sky is a deep, solid black.

- **I'm no Gene Kranz**

- **Robotics is Enabling the Architecture**

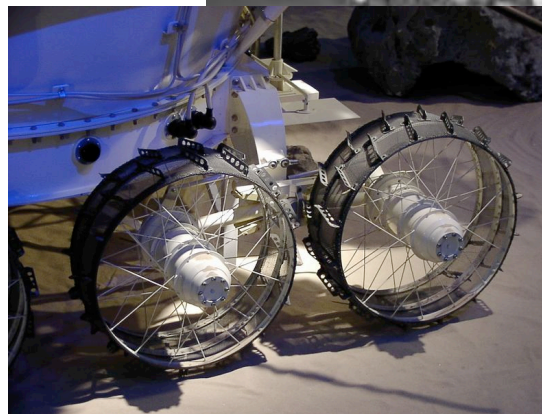
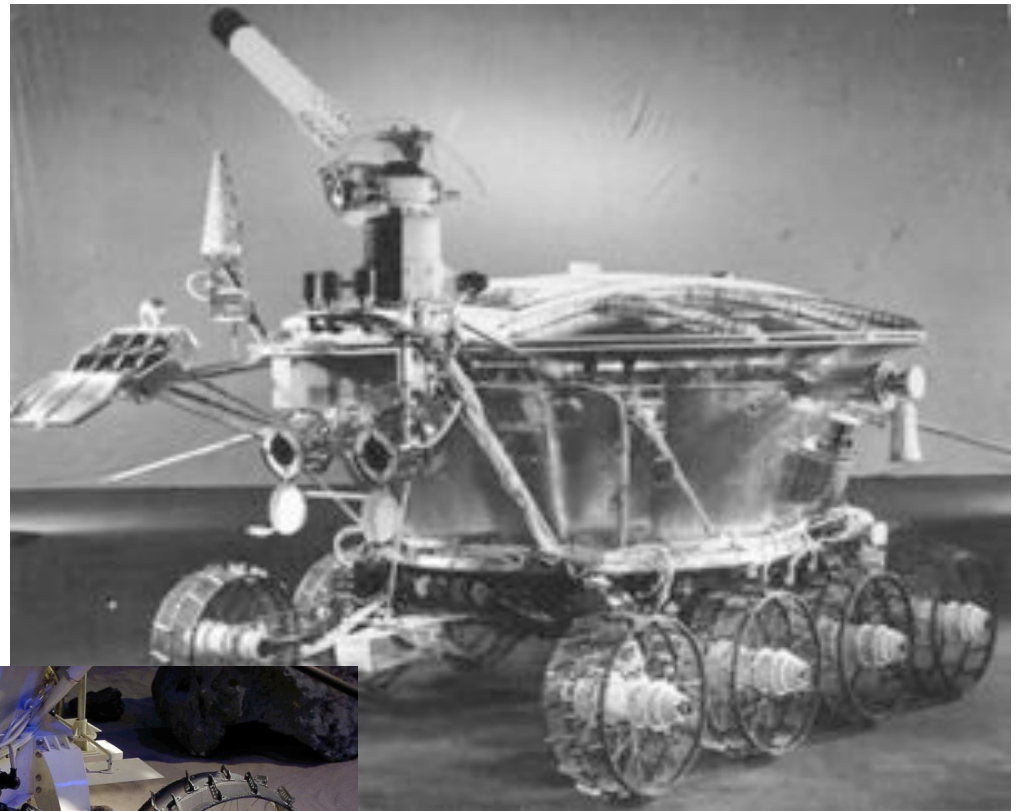
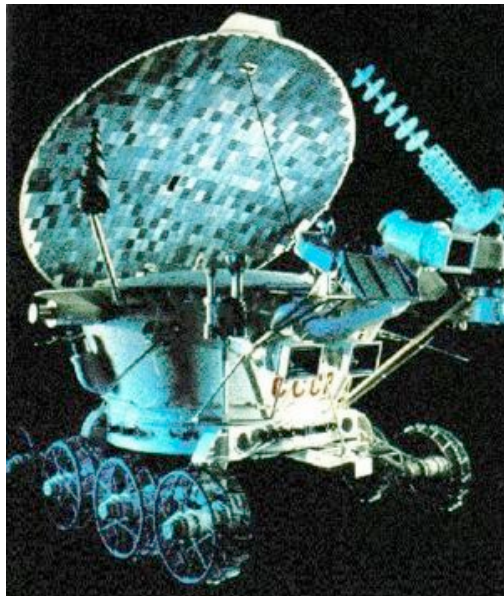
- **Turning those Concepts into Reality**



Lunokhod



- First Flight April 1970
- Lunokhod 1 & 2
- 840 Kg Mass
- 1 & 2 KPH
- 37 Km Life Range (L2)

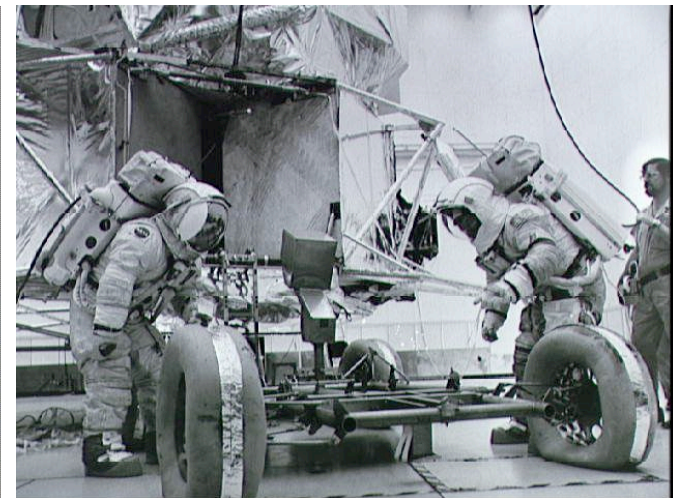
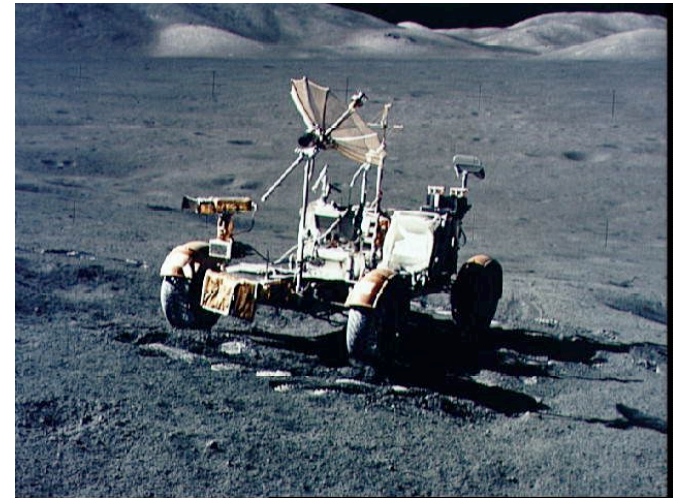




Apollo Lunar Roving Vehicle (LRV)



- First Flight April 1971
- Apollo 15, 16 & 17
- 210 Kg Mass
- 1/6g Payload 490 Kg
- 15 KPH
- 100 Km Life Range

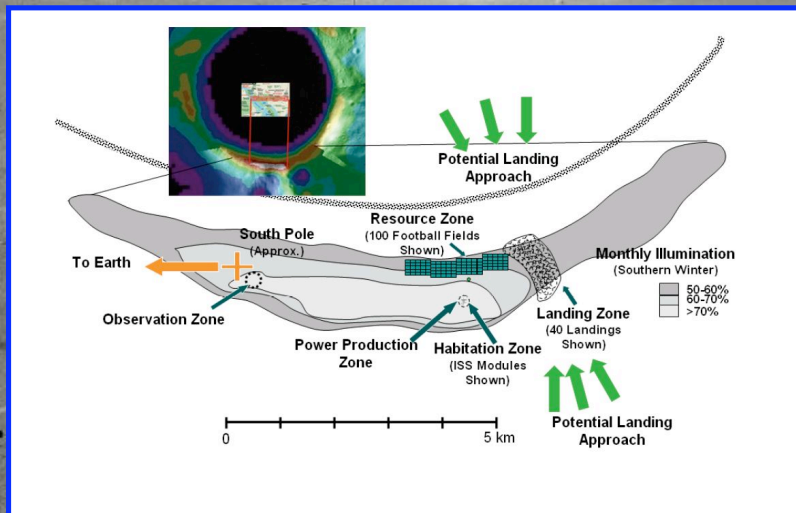




Apollo Lunar Roving Vehicle (LRV)



Robotic Perspective on NASA's Exploration Architecture



Surface Mobility

Surface Handling

Human-Systems Interaction



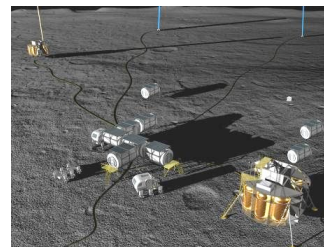


LAT-2's Architectural Options



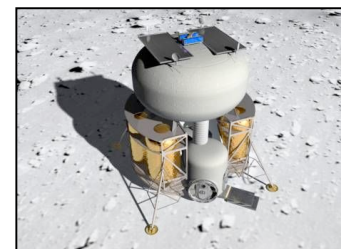
- Option 1 Results from LAT-1

- Option 2 “Mini-Habs”



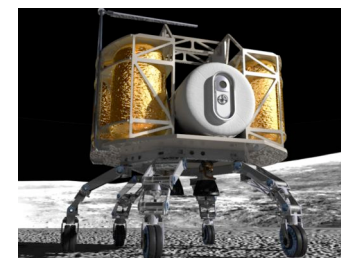
Habitats removed from Lander

- Option 3 “Monolithic Hab”



Habitat remains on Lander

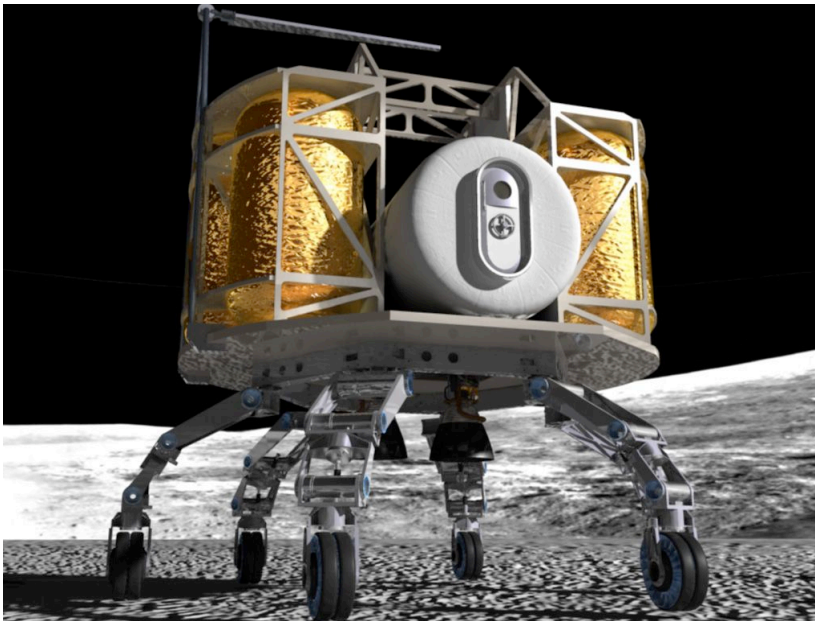
- Option 4 “Mobile Lander”



Mobile Habitats



Architecture Concept– Mobile Habitat

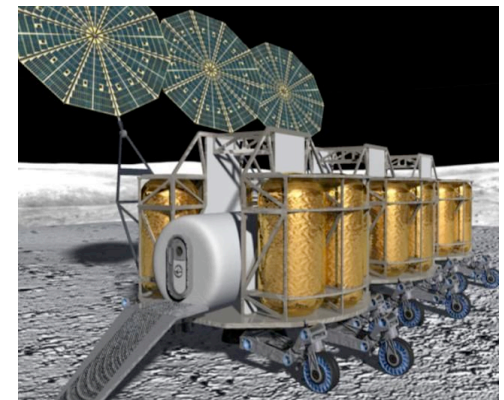
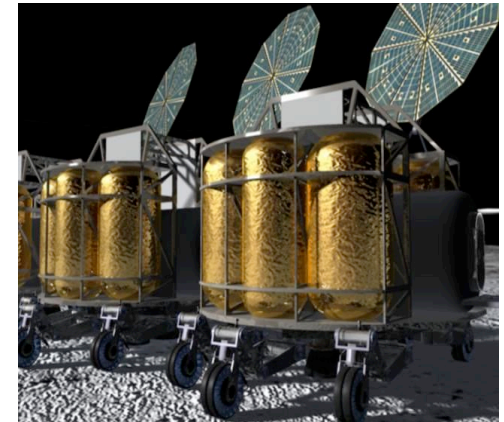


<20,000 Kg Payload

Integrated Power

Docking Together

1000+ Km Range





Architecture Concept– Small Pressurized Rover

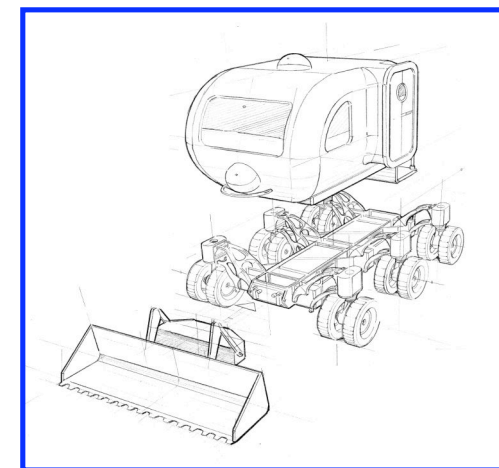
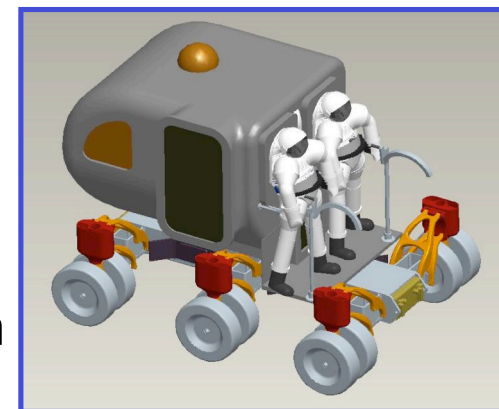


Fast Out the Door

Radiation Protection

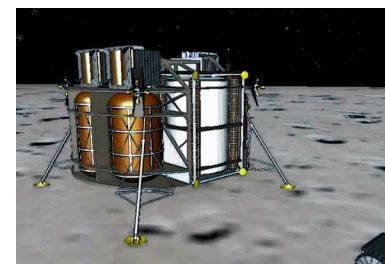
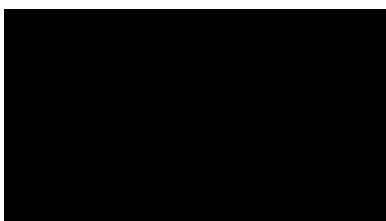
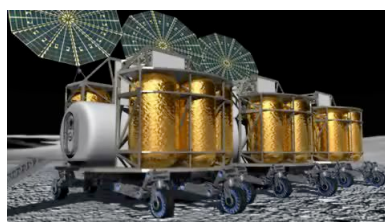
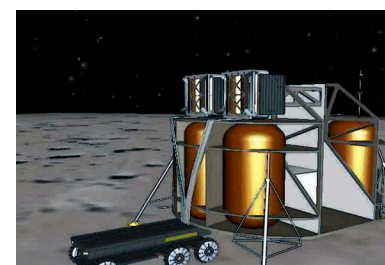
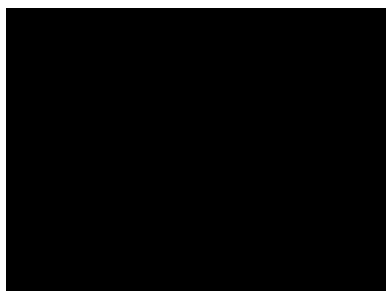
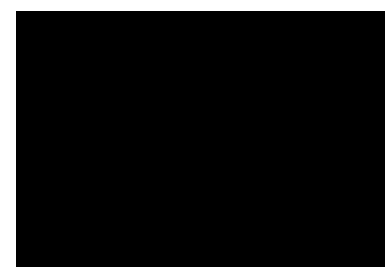
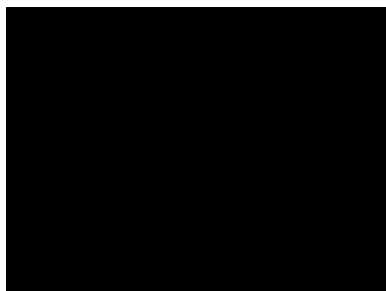
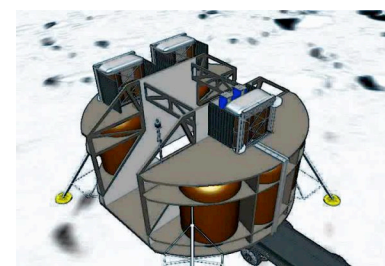
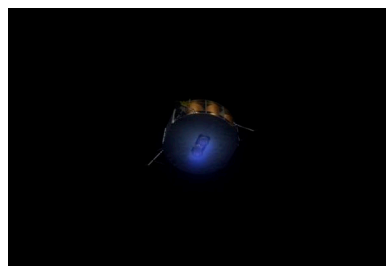
Hatch Docking

100+ Km Range





Architecture Concepts



NASA's Exploration Technology Development Program

Turning the Cartoons into Reality





Exploration Technology Development Program



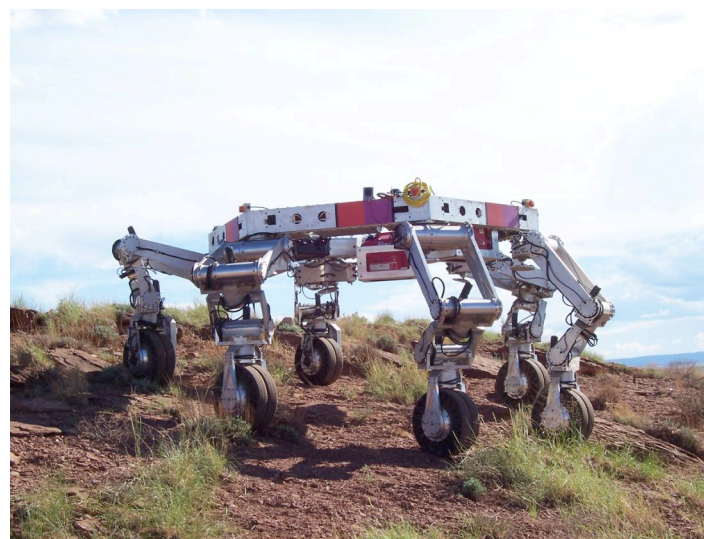
- The Exploration Systems Mission Directorate (ESMD) created this technology program in 2005.
 - Exploration Technology Development Program (ETDP)
 - ETDP Managed by ESMD Advanced Capabilities Division
 - Program office located at NASA Langley Research Center (LaRC)
 - Point of contact is Frank Peri (frank.peri-1@nasa.gov)
 - Dana Gould & Diane Hope are the Element Managers
- Broad portfolio of projects, with engineering focus
 - Propulsion, life support, power, human-robotics systems
 - Focused on technology for exploration needs
 - Crew Launch Vehicle (CEV)
 - Launch Systems
 - Surface Systems
- Driven by need dates and Technology Readiness Levels (TRL)
 - Exploration systems have development milestones
 - Technology is matured to be at TRL-6 by Preliminary Design Reviews (PDR's)



HRS Technology Description (ATHLETE)



- Leadership
 - NASA JPL
 - B. Wilcox
- Technologies
 - Wheel-on-limb Mobility
 - Mobility & manipulation
 - Active suspension
 - Payload offloading
 - Habitat docking
 - Hatch mating
- Collaborations
 - Stanford (Latome)
 - Michelin (Switzerland)

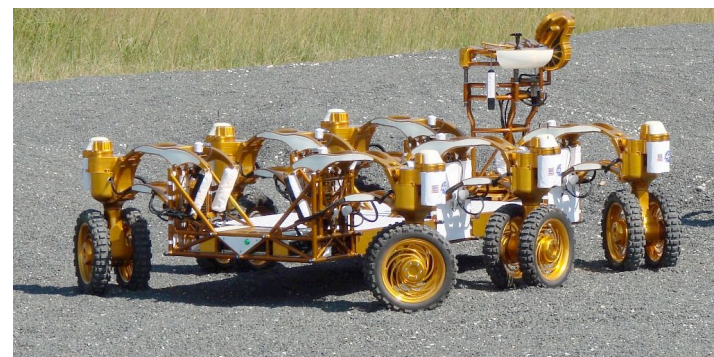




HRS Technology Description (Chariot)



- Leadership
 - NASA JSC
 - Ambrose, Bluethmann, Junkin
- Technologies
 - Novel chassis kinematics
 - Active/Passive suspension
 - Upright crew accommodations
 - Chassis leveling
 - Small Pressurized Rover Ops
- Collaborations
 - ETDP Advanced Suits
 - ETDP Thermal Control
 - ETDP ISRU
 - ETDP Power

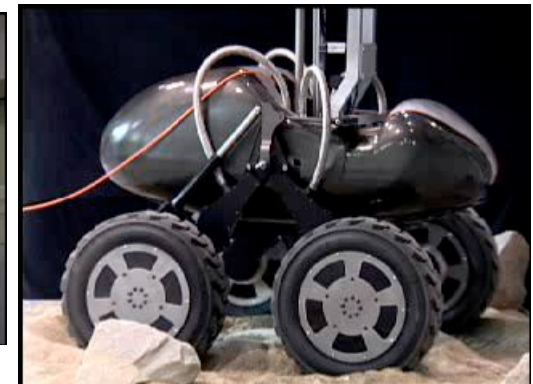




HRS Technology Description (Scarab)



- Leadership
 - NASA GRC & CMU
 - Whittaker, Caruso
- Technologies
 - Novel chassis kinematics
 - Integrated drill
 - Wheel spikes for drilling
 - Dark navigation
- Collaborations
 - CMU
 - NorCat
 - ETDP ISRU

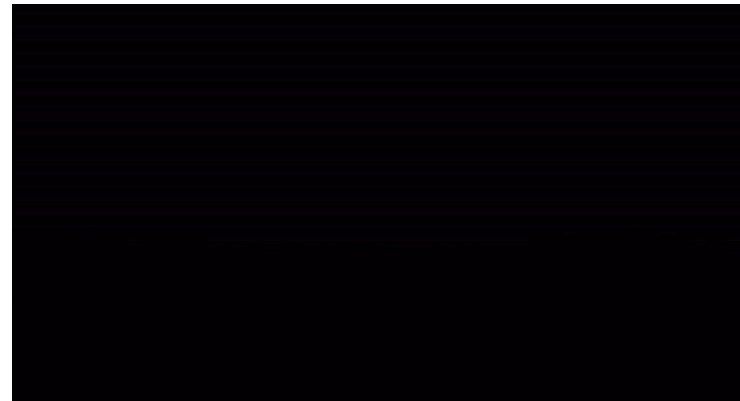




HRS Technology Description (Centaur)



- Leadership
 - NASA JSC
 - Ambrose, Diftler, Bluethmann
- Technologies
 - Autonomous Manipulation
 - Dexterity
 - Mobile Manipulation
 - Time Delayed Supervision
 - Astronaut Assistance
 - Surface Science
- Collaborations
 - UMass (Gruppen)
 - MIT (Brooks)
 - Vanderbilt (Peters)
 - Many earlier grants





Surface Scenario Video (2 minute)





Crater Access Scenario Video (2 minute)

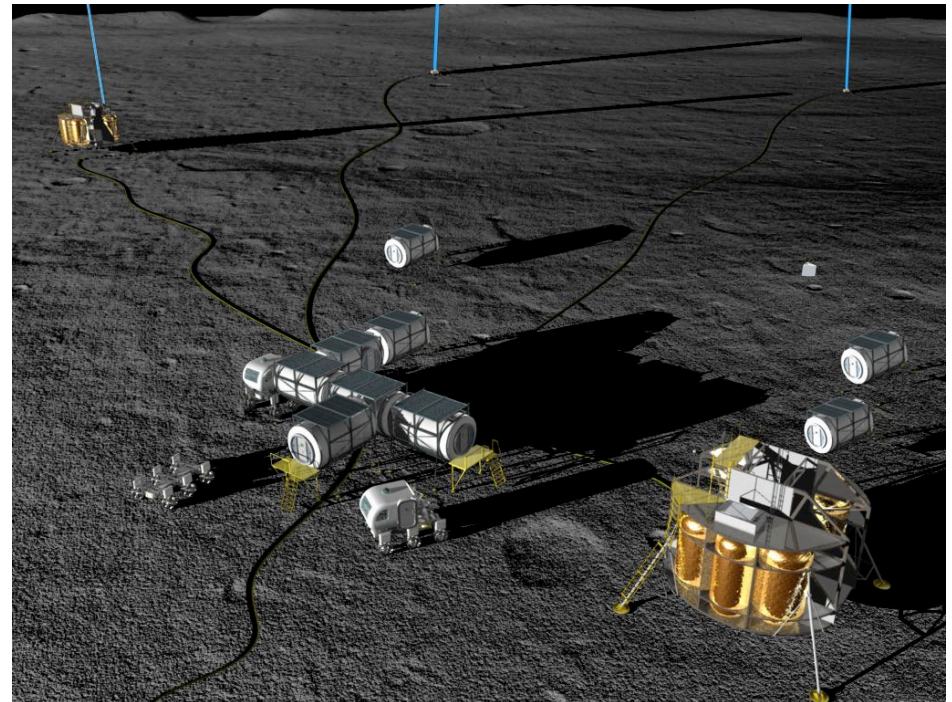




Plans for FY08



- 2008 Field Test
 - ATHLETE, Chariot, Scarab, K-10's, Crane
 - December Workshop
 - June Test
- New Technologies for 2009
 - Pressurized cabin mockup
 - New batteries & fuel cells
 - Chariot crew accommodations
 - 1/6g ATHLETE testing
 - New wheels
 - New drives
 - New supervision software





HRS Team (7 NASA Centers and 10+ Companies)

